

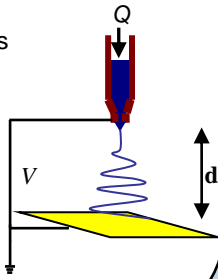
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ELECTROSPINNING

- ◆ Create nano-scale polymer fibers through the use of electric charge
- ◇ Induce charge on polymer solution through applied voltage
- ◇ When electrostatic forces overcome solution surface tension, a charged jet erupts from needle
- ◇ Normally undergoes 3 phases
 - Taylor Cone
 - Linear extension
 - Bending Instability
- ◇ Different collection methods based on desired orientation
- ◇ Current methods that yield oriented fibers are low output

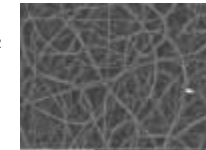
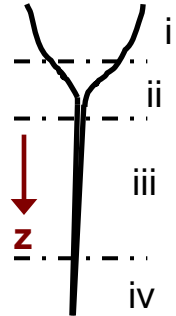


ELECTROHYDRODYNAMIC MODELING

- ◆ Motivation: Numerous potential applications
 - ◇ Tissue scaffolds, multi-functional composites, filtration, sensors, drug delivery...
- ◆ No model that can successfully link processing parameters with fiber diameter for multiple polymer-solvent systems!
- ◆ Helgeson et al. electrohydrodynamic model
 - ◇ Reduce dimensionless balance equations based on analogy to traditional uni-axial flow
 - ◇ Identify important forces in different sections of stable jet region
 - ◇ Experimentally verified for poly(ethylene oxide)-water system through high speed velocimetry

STABLE JET REGIONS

- ◆ i. Taylor Cone
- ◆ ii. Jet Initiation
 - ◇ Strain Hardening
 - ◇ Large increase in extensional viscosity
- ◆ iii. Jet Stretching
 - ◇ Reach pseudo-steady state extensional viscosity
 - ◇ $R \sim z^{-1/2}$, $v \sim z$
- ◆ Jet Thinning
 - ◇ $R \sim z^{-1/4}$, $v \sim z^{1/2}$



Representative non-woven mat, x1000

EXPERIMENTAL

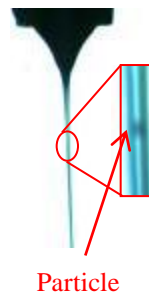
- ◆ **Goal:** Explicitly verify observed scaling laws for a completely different electrospinning system
- ◆ Poly(ethylene oxide)-Chloroform
 - ◇ Linear jet—No bending instability!
 - ◇ Collection of highly spatially oriented fibers



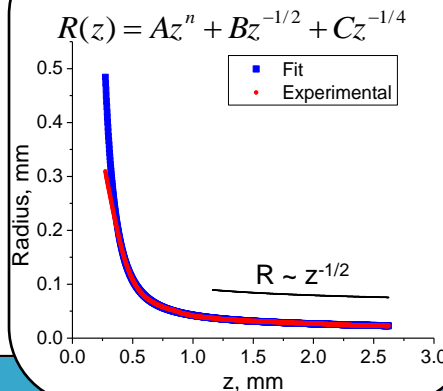
PEO-Chloroform, x1000

HIGH SPEED IMAGING

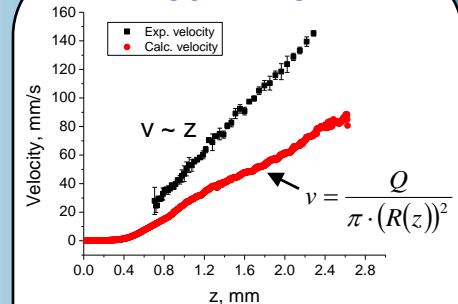
- ◆ High speed images to track particles in the jet
 - ◇ Hollow silica (10 μm)
 - ◇ 2000 fps
 - ◇ 250 μs exposure
- ◆ Observations:
 - ◇ Solvent evaporation seemed to play large role
 - ◇ Formation of polymer 'skin' on cone region
 - ◇ Steady jet difficult to achieve



RADIUS FITTING



VELOCITY PROFILE



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